

JORDAN DERIVATIONS OF SEMIPRIME RINGS AND NONCOMMUTATIVE BANACH ALGEBRAS, II

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ABSTRACT. Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that $D(x)^2[D(x), x] \in \text{rad}(A)$ or $[D(x), x]D(x)^2 \in \text{rad}(A)$ for all $x \in A$. In this case, we have $D(A) \subseteq \text{rad}(A)$.

1. INTRODUCTION

Throughout, R represents an associative ring and A will be a complex Banach algebra. We write $[x, y]$ for the commutator $xy - yx$ for x, y in a ring. Let $\text{rad}(R)$ denote the (*Jacobson*) *radical* of a ring R . And a ring R is said to be (*Jacobson*) *semisimple* if its Jacobson radical $\text{rad}(R)$ is zero.

A ring R is called *n-torsion free* if $nx = 0$ implies $x = 0$. Recall that R is *prime* if $aRb = (0)$ implies that either $a = 0$ or $b = 0$, and is *semiprime* if $aRa = (0)$ implies $a = 0$. On the other hand, let X be an element of a normed algebra. Then for every $a \in X$ the *spectral radius* of a , denoted by $r(a)$, is defined by $r(a) = \inf\{\|a^n\|^{\frac{1}{n}} : n \in \mathbb{N}\}$. It is well-known that the following theorem holds: if a be an element of a normed algebra, then $r(a) = \lim_{n \rightarrow \infty} \|a^n\|^{\frac{1}{n}}$ (see F.F. Bonsall and J. Duncan [1]).

An additive mapping D from R to R is called a *derivation* if $D(xy) = D(x)y + xD(y)$ holds for all $x, y \in R$. And an additive mapping D from R to R is called a *Jordan derivation* if $D(x^2) = D(x)x + xD(x)$ holds for all $x \in R$.

B.E. Johnson and A.M. Sinclair [5] have proved that any linear derivation on a semisimple Banach algebra is continuous. A result of I.M. Singer and J. Wermer [9] states that every continuous linear derivation on a commutative Banach algebra maps the algebra into its radical. From these two results, we can conclude that there are no nonzero linear derivations on a commutative semisimple Banach algebra.

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M.P. Thomas [10] has proved that any linear derivation on a commutative Banach algebra maps the algebra into its radical.

J. Vukman [11] has proved the following: let R be a 2-torsion free prime ring. If $D : R \rightarrow R$ is a derivation such that $[D(x), x]D(x) = 0$ for all $x \in R$, then $D = 0$.

Moreover, using the above result, he has proved that the following holds: let A be a noncommutative semisimple Banach algebra. Suppose that $[D(x), x]D(x) = 0$ holds for all $x \in A$. In this case, $D = 0$.

The author [6] has showed that the following results hold: let R be a 3!-torsion free semiprime ring. Suppose there exists a Jordan derivation $D : R \rightarrow R$ such that

$$[D(x), x]D(x)[D(x), x] = 0$$

for all $x \in R$. In this case, we have $[D(x), x]^5 = 0$ for all $x \in R$.

And, the author [7] has showed that the following results hold: let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that $D(x)[D(x), x]D(x) \in \text{rad}(A)$ for all $x \in A$. In this case, we have $D(A) \subseteq \text{rad}(A)$.

In this paper, our first aim is to prove the following results in the ring theory in order to apply it to the Banach algebra theory:

let R be a 7!-torsion free semiprime ring.

(i) Suppose there exists a Jordan derivation $D : R \rightarrow R$ such that

$$D(x)^2[D(x), x] = 0$$

for all $x \in R$. In this case, we obtain $[D(x), x]^7 = 0$ for all $x \in R$.

(ii) Suppose there exists a Jordan derivation $D : R \rightarrow R$ such that

$$[D(x), x]D(x)^2 = 0$$

for all $x \in R$. In this case, we obtain $[D(x), x]^7 = 0$ for all $x \in R$.

Using the above results, we generalize J. Vukman's result [11] as follows: let A be a noncommutative Banach algebra and let $D : A \rightarrow A$ be a continuous linear Jordan derivation.

(iii) Suppose that $D(x)^2[D(x), x] \in \text{rad}(A)$ holds for all $x \in A$. In this case, $D(A) \subseteq \text{rad}(A)$.

(iv) Suppose that $[D(x), x]D(x)^2 \in \text{rad}(A)$ holds for all $x \in A$. In this case, $D(A) \subseteq \text{rad}(A)$.

2. PRELIMINARIES AND RESULTS

The following lemma is due to L.O. Chung and J. Luh [4].

Lemma 2.1. *Let R be a $n!$ -torsion free ring. Suppose there exist elements $y_1, y_2, \dots, y_{n-1}, y_n$ in R such that $\sum_{k=1}^n t^k y_k = 0$ for all $t = 1, 2, \dots, n$. Then we have $y_k = 0$ for every positive integer k with $1 \leq k \leq n$.*

The following theorem is due to M. Brešar [3].

Theorem 2.2. *Let R be a 2-torsion free semiprime ring and let $D : R \rightarrow R$ be a Jordan derivation. In this case, D is a derivation.*

We write $Q(A)$ for the set of all quasinilpotent elements in A . M. Brešar [2] has proved the following theorem.

Theorem 2.3. *Let D be a bounded derivation of a Banach algebra A . Suppose that $[D(x), x] \in Q(A)$ for every $x \in A$. Then D maps A into $rad(A)$.*

After this, by S_m we denote the set $\{k \in \mathbb{N} \mid 1 \leq k \leq m\}$ where m is a positive integer.

We need Theorem 2.4 and 2.5 to obtain the main theorems for Banach algebra theory.

Theorem 2.4. *Let R be a 7!-torsion free noncommutative semiprime ring. Suppose there exists a Jordan derivation $D : R \rightarrow R$ such that*

$$D(x)^2[D(x), x] = 0$$

for all $x \in R$. In this case we have $[D(x), x]^7 = 0$ for all $x \in R$.

Proof. By Theorem 2.2, we can see that D is a derivation on R . For simplicity, we shall denote the maps $B : R \times R \rightarrow R, f, g : R \rightarrow R$ by $B(x, y) \equiv [D(x), y] + [D(y), x], f(x) \equiv [D(x), x], g(x) \equiv [f(x), x]$ for all $x, y \in R$ respectively. Then we have the basic properties:

$$\begin{aligned} B(x, y) &= B(y, x), B(x, yz) = B(x, y)z + yB(x, z) + D(y)[z, x] + [y, x]D(z), \\ B(x, x) &= 2f(x), B(xy, z) = B(y, z)x + zB(y, x) + D(z)[x, y] + [z, y]D(x), \\ B(x, x^2) &= 2(f(x)x + xf(x)), x, y, z \in R. \end{aligned}$$

After this, we use the above relations without specific reference. By assumption,

$$(1) \quad D(x)^2 f(x) = 0, x \in R$$

Replacing $x + ty$ for x in (1), we have

$$\begin{aligned}
 & D(x + ty)^2[D(x + ty), x + ty] \\
 & \equiv D(x)^2f(x) + t\{D(y)D(x)f(x) + D(x)D(y)B(x, y) \\
 & \quad + D(x)^2B(x, y)\} + t^2H_1(x, y) + t^3H_2(x, y) \\
 (2) \quad & + t^4D(y)^2f(y) = 0, \quad x, y \in R, t \in S_3
 \end{aligned}$$

where H_i , $1 \leq i \leq 2$, denotes the term satisfying the identity (2).

From (1) and (2), we obtain

$$\begin{aligned}
 & t\{D(y)D(x)f(x) + D(x)D(y)f(x) + D(x)^2B(x, y)\} \\
 (3) \quad & + t^2H_1(x, y) + t^3H_2(x, y) = 0, \quad x, y \in R, t \in S_3.
 \end{aligned}$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (3) yields

$$(4) \quad D(y)D(x)f(x) + D(x)D(y)f(x) + D(x)^2B(x, y) = 0, \quad x, y \in R.$$

Let $y = x^2$ in (4). Then using (1), we have

$$\begin{aligned}
 & (D(x)x + xD(x))D(x)f(x) + D(x)(D(x)x + xD(x))f(x) \\
 & \quad + 2D(x)^2(f(x)x + xf(x)) \\
 & = f(x)D(x)f(x) + (f(x)D(x) + D(x)f(x))f(x) + f(x)D(x)f(x) \\
 & \quad + 2(f(x)D(x) + D(x)f(x))f(x) \\
 (5) \quad & = 5f(x)D(x)f(x) + 3D(x)f(x)^2 = 0, \quad x \in R.
 \end{aligned}$$

From (1), we arrive at

$$\begin{aligned}
 (6) \quad & 0 = [D(x)^2f(x), x] \\
 & = f(x)D(x)f(x) + D(x)f(x)^2 + D(x)^2g(x), \quad x \in R.
 \end{aligned}$$

From (5) and (6), we get

$$(7) \quad 2f(x)D(x)f(x) - 3D(x)^2g(x) = 0, \quad x \in R.$$

Combining (5) with (7),

$$3(2D(x)f(x)^2 + 5D(x)^2g(x)) = 0, \quad x \in R.$$

Since R is 3!-torsion-free, the above relation gives

$$(8) \quad 2D(x)f(x)^2 + 5D(x)^2g(x) = 0, \quad x \in R.$$

Left multiplication of (8) by $D(x)$ leads to

$$(9) \quad 2D(x)^2f(x)^2 + 5D(x)^3g(x) = 0, \quad x \in R.$$

Comparing (1) and (9), we arrive at

$$(10) \quad 5D(x)^3g(x) = 0, \quad x \in R.$$

Since R is 5!-torsion-free, (10) gives

$$(11) \quad D(x)^3g(x) = 0, \quad x \in R.$$

Writing xy for y in (4), we get

$$(12) \quad \begin{aligned} & xD(y)D(x)f(x) + D(x)yD(x)f(x) + D(x)xD(y)f(x) + D(x)^2yf(x) \\ & + D(x)^2(xB(x,y) + 2f(x)y + D(x)[y,x]) = 0. \quad x, y \in R. \end{aligned}$$

Left multiplication of (4) by x leads to

$$(13) \quad xD(y)D(x)f(x) + xD(x)D(y)f(x) + xD(x)^2B(x,y) = 0, \quad x, y \in R.$$

From (12) and (13), we arrive at

$$(14) \quad \begin{aligned} & D(x)yD(x)f(x) + f(x)D(y)f(x) + D(x)^2yf(x) + (f(x)D(x) \\ & + D(x)f(x))B(x,y) + 2D(x)^2f(x)y + D(x)^3[y,x] = 0. \quad x, y \in R. \end{aligned}$$

By (1) and (14), it is obvious that

$$(15) \quad \begin{aligned} & D(x)yD(x)f(x) + f(x)D(y)f(x) + D(x)^2yf(x) + (f(x)D(x) \\ & + D(x)f(x))B(x,y) + D(x)^3[y,x] = 0, \quad x, y \in R. \end{aligned}$$

Replacing yx for y in (15), it follows from that

$$(16) \quad \begin{aligned} & D(x)yxD(x)f(x) + f(x)D(y)xf(x) + f(x)yD(x)f(x) \\ & + D(x)^2yxf(x) + (f(x)D(x) + D(x)f(x))(B(x,y)x + 2yf(x) + [y,x]D(x)) \\ & + D(x)^3[y,x]x = 0. \quad x, y \in R. \end{aligned}$$

Right multiplication of (15) by x leads to

$$(17) \quad \begin{aligned} & D(x)yD(x)f(x)x + f(x)D(y)f(x)x + D(x)^2yf(x)x \\ & + (f(x)D(x) + D(x)f(x))B(x,y)x + D(x)^3[y,x]x = 0, \quad x, y \in R. \end{aligned}$$

Combining (16) with (17), we see that

$$(18) \quad \begin{aligned} & -D(x)y(f(x)^2 + D(x)g(x)) - f(x)D(y)g(x) + f(x)yD(x)f(x) \\ & - D(x)^2yg(x) + 2(f(x)D(x) + D(x)f(x))yf(x) \\ & + (f(x)D(x) + D(x)f(x))[y,x]D(x) = 0. \quad x, y \in R. \end{aligned}$$

Left multiplication of (18) by $D(x)^2$ leads to

$$\begin{aligned} & -D(x)^3y(f(x)^2 + D(x)g(x)) - D(x)^2f(x)D(y)g(x) - D(x)^4yg(x) \\ & + D(x)^2f(x)yD(x)f(x) + 2D(x)^2(f(x)D(x) \\ (19) \quad & + D(x)f(x))yf(x) + D(x)^2(f(x)D(x) + D(x)f(x))[y, x]D(x) = 0, \quad x, y \in R. \end{aligned}$$

Comparing (1) and (19), we get

$$(20) \quad D(x)^3y(f(x)^2 + D(x)g(x)) + D(x)^4yg(x) = 0, \quad x, y \in R.$$

Substituting $yD(x)^2$ for y in (20), we have

$$(21) \quad D(x)^3y(D(x)^2f(x)^2 + D(x)^3g(x)) + D(x)^4yD(x)^2g(x) = 0, \quad x, y \in R.$$

From (1), (11) and (21), it is clear that

$$(22) \quad D(x)^4yD(x)^2g(x) = 0, \quad x, y \in R.$$

Using (8), it follows from (22) that

$$(23) \quad 2D(x)^4yD(x)^2g(x) = D(x)^4y(-5D(x)^2g(x)) = 0, \quad x, y \in R.$$

Thus since R is 2-torsion-free, (23) gives

$$(24) \quad D(x)^4yD(x)^2g(x) = 0, \quad x, y \in R.$$

Combining (8) with (24) that

$$(25) \quad 2D(x)^4yD(x)f(x)^2 = -5D(x)^4yD(x)^2g(x) = 0, \quad x, y \in R.$$

And so, since R is 2-torsion-free, (25) yields

$$(26) \quad D(x)^4yD(x)f(x)^2 = 0, \quad x, y \in R.$$

From (7) and (24), we have

$$\begin{aligned} & 2D(x)^4yf(x)D(x)f(x) = D(x)^4y(3D(x)^2g(x)) \\ (27) \quad & = 3D(x)^4yD(x)^2g(x) = 0, \quad x, y \in R. \end{aligned}$$

It follows from (27) that

$$(28) \quad D(x)^4yf(x)D(x)f(x) = 0, \quad x, y \in R$$

since R is 2-torsion-free. Writing $yf(x)D(x)f(x)z$ for y in (20), we have

$$\begin{aligned} & D(x)^3yf(x)D(x)f(x)z(f(x)^2 + D(x)g(x)) \\ (29) \quad & + D(x)^4yf(x)D(x)f(x)zg(x) = 0, \quad x, y, z \in R. \end{aligned}$$

From (28) and (29), we obtain

$$(30) \quad D(x)^3 y f(x) D(x) f(x) z (f(x)^2 + D(x) g(x)) = 0, \quad x, y, z \in R.$$

Letting $zD(x)$ in z in (30), we get

$$(31) \quad D(x)^3 y f(x) D(x) f(x) z (D(x) f(x)^2 + D(x)^2 g(x)) = 0, \quad x, y, z \in R.$$

Using (6), the relation (31) gives

$$(32) \quad D(x)^3 y f(x) D(x) f(x) z f(x) D(x) f(x) = 0, \quad x, y, z \in R.$$

Putting $zD(x)^3 y$ instead of z in (32),

$$(33) \quad D(x)^3 y f(x) D(x) f(x) z (D(x)^3 y f(x) D(x) f(x)) = 0, \quad x, y, z \in R.$$

Since R is semiprime, we have

$$(34) \quad D(x)^3 y f(x) D(x) f(x) = 0, \quad x, y \in R.$$

Replacing $x + tz$ for x in (34), we have

$$\begin{aligned} & D(x + tz)^3 y f(x + tz) D(x + tz) f(x + tz) \\ \equiv & D(x)^3 y f(x) D(x) f(x) \\ & + t\{(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))yf(x)D(x)f(x) \\ & + D(x)^3y(B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z))\} \\ & + t^2I_1(x, y, z) + t^3I_2(x, y, z) + t^4I_3(x, y, z) \\ & + t^5I_4(x, y, z) + t^6I_5(x, y, z) + t^7I_6(x, y, z) \\ (35) \quad & + t^8D(z)^3yf(z)D(z)f(z) = 0, \quad x, y, z \in R, \quad t \in S_7 \end{aligned}$$

where I_i , $1 \leq i \leq 6$, denotes the term satisfying the identity (35).

From (34) and (35), we obtain

$$\begin{aligned} & t\{(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))yf(x)D(x)f(x) \\ & + D(x)^3y(B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z))\} \\ & + t^2I_1(x, y, z) + t^3I_2(x, y, z) + t^4I_3(x, y, z) \\ (36) \quad & + t^5I_4(x, y, z) + t^6I_5(x, y, z) + t^7I_6(x, y, z) = 0, \quad x, y, z \in R, \quad t \in S_7. \end{aligned}$$

Since R is 7!-torsion-free by assumption, by Lemma 2.1 the relation (36) yields

$$\begin{aligned} & (D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))yf(x)D(x)f(x) \\ & + D(x)^3y(B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z)) \\ (37) \quad & = 0, \quad x, y, z \in R. \end{aligned}$$

Substituting $yf(x)D(x)f(x)w$ for y in (37), we obtain

$$\begin{aligned}
 & (D(z)D(x)^2 + D(x)D(z)D(x) \\
 & + D(x)^2D(z))yf(x)D(x)f(x)w(f(x)D(x)f(x) \\
 & + D(x)^3yf(x)D(x)f(x)w(B(x, z)D(x)f(x) \\
 (38) \quad & + f(x)D(z)f(x) + f(x)D(x)B(x, z)) = 0, \quad x, y, z, w \in R.
 \end{aligned}$$

Combining (34) with (38), we get

$$\begin{aligned}
 & (D(z)D(x)^2 + D(x)D(z)D(x) \\
 (39) \quad & + D(x)^2D(z))yf(x)D(x)f(x))wf(x)D(x)f(x) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Writing $w(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))y$ for w in (39), we obtain

$$\begin{aligned}
 & (D(z)D(x)^2 + D(x)D(z)D(x) \\
 & + D(x)^2D(z))yf(x)D(x)f(x)w(D(z)D(x)^2 + D(x)D(z)D(x) \\
 (40) \quad & + D(x)^2D(z))yf(x)D(x)f(x) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Since R is semiprime, it follows from (40) that

$$\begin{aligned}
 & (D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))yf(x)D(x)f(x) \\
 (41) \quad & = 0, \quad x, y, z \in R, \quad t \in S_7.
 \end{aligned}$$

Replacing $x + tu$ for x in (41), we have

$$\begin{aligned}
 & (D(z)D(x + tu)^2 + D(x + tu)D(z)D(x + tu) \\
 & + D(x + tu)^2D(z))yf(x + tu)D(x + tu)f(x + tu) \\
 \equiv & (D(z)D(x)^2 + D(x)D(z)D(x) \\
 & + D(x)^2D(z))yf(x)D(x)f(x) \\
 & + t\{(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
 & + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x) \\
 & + (D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))y(B(x, u)D(x)f(x) \\
 & + f(x)D(u)f(x) + f(x)D(x)B(x, u))\} \\
 & + t^2J_1(x, y, z, u) + t^3J_2(x, y, z, u) + t^4J_3(x, y, z, u) \\
 & + t^5J_4(x, y, z, u) + t^6J_5(x, y, z, u) \\
 & + t^7(D(z)D(u)^2 + D(u)D(z)D(u) \\
 (42) \quad & + D(u)^2D(z))yf(u)D(u)f(u) = 0, \quad x, y, z, u \in R, \quad t \in S_6
 \end{aligned}$$

where J_i , $1 \leq i \leq 5$, denotes the term satisfying the identity (42).

From (41) and (42), we obtain

$$\begin{aligned}
 & t\{(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
 & + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x) \\
 & + (D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))y(B(x, u)D(x)f(x) \\
 & + f(x)D(u)f(x) + f(x)D(x)B(x, u))\} \\
 & + t^2 J_1(x, y, z, u) + t^3 J_2(x, y, z, u) + t^4 J_3(x, y, z, u) \\
 (43) \quad & + t^5 J_4(x, y, z, u) + t^6 J_5(x, y, z, u) = 0, \quad x, y, z, u \in R, \quad t \in S_6.
 \end{aligned}$$

Since R is 6!-torsion-free by assumption, by Lemma 2.1 the relation (43) yields

$$\begin{aligned}
 & (D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
 & + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x) \\
 & + (D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))y(B(x, u)D(x)f(x) \\
 (44) \quad & + f(x)D(u)f(x) + f(x)D(x)B(x, u)) = 0, \quad x, y, z, u \in R.
 \end{aligned}$$

Substituting $yf(x)D(x)f(x)w$ for y in (44), we obtain

$$\begin{aligned}
 & (D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) \\
 & + (D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x)wf(x)D(x)f(x) \\
 & + (D(z)D(x)^2 + D(x)D(z)D(x) \\
 & + D(x)^2D(z))yf(x)D(x)f(x)w(B(x, u)D(x)f(x) \\
 (45) \quad & + f(x)D(u)f(x) + f(x)D(x)B(x, u)) = 0, \quad x, y, z, u, w \in R.
 \end{aligned}$$

Combining (41) with (45), we get

$$\begin{aligned}
 & (D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) \\
 & + (D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x)wf(x)D(x)f(x) \\
 (46) \quad & = 0 \quad x, y, z, u, w \in R, \quad t \in S_6.
 \end{aligned}$$

Replacing $w(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z))y$ for w in (46), we obtain

$$\begin{aligned}
 & (D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
 & + D(x)D(z)D(u) + (D(u)D(x) \\
 & + D(x)D(u))D(z))yf(x)D(x)f(x)w(D(z)(D(u)D(x)
 \end{aligned}$$

$$(47) \quad \begin{aligned} &+D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) \\ &+(D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x) = 0, \quad u, w, x, y, z \in R. \end{aligned}$$

Since R is semiprime, it follows from (47) that

$$(48) \quad \begin{aligned} &(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) \\ &+(D(u)D(x) + D(x)D(u))D(z))yf(x)D(x)f(x) = 0, \quad x, y, z, u \in R. \end{aligned}$$

Starting from (48), we have the following relation

$$(49) \quad \begin{aligned} &(D(z)(D(u)D(v) + D(v)D(u)) + D(u)D(z)D(v) \\ &+D(v)D(z)D(u) + (D(u)D(v) \\ &+D(v)D(u))D(z))yf(x)D(x)f(x) = 0, \quad x, y, z, u, v \in R \end{aligned}$$

in the same fashion that makes it possible to obtain (48) from (41). And so, setting $v = u = z$ in (49), it is obvious that

$$6D(z)^3yf(x)D(x)f(x) = 0, \quad x, y, z \in R.$$

Since R is 3!-torsion-free, replacing x, z, w for z, x, y in the above relation respectively, we obtain

$$(50) \quad D(x)^3wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Replacing $x + ty$ for x in (50), we have

$$(51) \quad \begin{aligned} &D(x + ty)^3wf(z)D(z)f(z) \\ &\equiv D(x)^3wf(z)D(z)f(z) + t\{(D(y)D(x)^2 \\ &+D(x)D(y)D(x) + D(x)^2D(y))wf(z)D(z)f(z)\} \\ &+t^2K(x, y)wf(z)D(z)f(z) + t^3D(y)^3wf(z)D(z)f(z) \\ &= 0, \quad w, x, y, z \in R, \quad t \in S_3 \end{aligned}$$

where $K(x, y)$ denotes the term satisfying the identity (51).

From (50) and (51), we obtain

$$(52) \quad \begin{aligned} &t\{(D(y)D(x)^2 + D(x)D(y)D(x) + D(x)^2D(y))wf(z)D(z)f(z)\} \\ &+t^2K(x, y)wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R, \quad t \in S_3. \end{aligned}$$

Since R is 2!-torsion-free by assumption, by Lemma 2.1 the relation (52) yields

$$(53) \quad \begin{aligned} &(D(y)D(x)^2 + D(x)D(y)D(x) + D(x)^2D(y))wf(z)D(z)f(z) \\ &= 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting x^2 for y in (53), we obtain

$$(54) \quad \begin{aligned} & (D(x)x D(x)^2 + x D(x)^3 + D(x)(D(x)x + x D(x))D(x) \\ & + D(x)^2(D(x)x + x D(x))w f(z)D(z)f(z) = 0, w, x, z \in R. \end{aligned}$$

Combining (50) with (54), we get

$$(55) \quad 2(f(x)D(x)^2 - D(x)^2 f(x))w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Since R is 2!-torsion-free, the relation (55) yields

$$(56) \quad (f(x)D(x)^2 - D(x)^2 f(x))w f(z)D(z)f(z) = 0, w, x, z \in R.$$

From (1) and (56), we have

$$(57) \quad f(x)D(x)^2 w f(z)D(z)f(z) = 0, w, x, z \in R.$$

On the other hand, substituting xw for w in (50), we obtain

$$(58) \quad D(x)^3 x w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Left multiplication of (50) by x gives

$$(59) \quad x D(x)^3 w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Combining (58) with (59), we get

$$(60) \quad \begin{aligned} & [D(x)^3, x]w f(z)D(z)f(z) \\ & = (f(x)D(x)^2 + D(x)f(x)D(x) + D(x)^2 f(x))w f(z)D(z)f(z) = 0, x \in R. \end{aligned}$$

From (1),(57) and (60), it is obvious that

$$(61) \quad D(x)f(x)D(x)w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Writing xw for w in (57), we obtain

$$(62) \quad f(x)D(x)^2 x w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Left multiplication of (57) by x gives

$$(63) \quad x f(x)D(x)^2 w f(z)D(z)f(z) = 0, w, x, z \in R.$$

Comparing (62) and (63), we get

$$(64) \quad \begin{aligned} & [f(x)D(x)^2, x]w f(z)D(z)f(z) \\ & = (g(x)D(x)^2 + f(x)^2 D(x) + f(x)D(x)f(x))w f(z)D(z)f(z) = 0, x \in R. \end{aligned}$$

Left multiplication of (53) by $D(x)^2$ gives

$$(65) \quad \begin{aligned} & (D(x)^2D(y)D(x)^2 + D(x)^3D(y)D(x) \\ & + D(x)^4D(y))wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

From (50) and (65), we obtain

$$(66) \quad D(x)^2D(y)D(x)^2wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R.$$

Putting $yD(x)^2u$ instead of y in (66), we have

$$(67) \quad \begin{aligned} & D(x)^2(D(y)D(x)^2u + yD(D(x)^2)u \\ & + yD(x)^2D(u))D(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, y, z \in R. \end{aligned}$$

Combining (66) with (67), we get

$$(68) \quad D(x)^2yD(D(x)^2)uD(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, y, z \in R.$$

Substituting $wf(z)D(z)f(z)y$ for y in (53), we obtain

$$(69) \quad \begin{aligned} & D(x)^2wf(z)D(z)f(z)yD(D(x)^2)uD(x)^2wf(z)D(z)f(z) \\ & = 0, \quad u, w, x, y, z \in R. \end{aligned}$$

Left multiplication of (69) by $D(D(x)^2)u$ gives

$$(70) \quad \begin{aligned} & D(D(x)^2)uD(x)^2wf(z)D(z)f(z)y(D(D(x)^2)uD(x)^2wf(z)D(z)f(z)) \\ & = 0, \quad u, w, x, y, z \in R. \end{aligned}$$

Since R is semiprime, the relation (70) yields

$$(71) \quad D(D(x)^2)uD(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, z \in R.$$

The relation (71) yields

$$(72) \quad (D^2(x)D(x) + D(x)D^2(x))uD(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, z \in R.$$

Left multiplication of (72) by $D(x)$ gives

$$(73) \quad (D(x)D^2(x)D(x) + D(x)^2D^2(x))uD(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, z \in R.$$

Writing $D(x)$ for y in (53), we have

$$(74) \quad \begin{aligned} & (D^2(x)D(x)^2 + D(x)D^2(x)D(x) + D(x)^2D^2(x))wf(z)D(z)f(z) \\ & = 0, \quad w, x, z \in R. \end{aligned}$$

Substituting $uD(x)^2w$ for w in (74), we obtain

$$(75) \quad \begin{aligned} & (D^2(x)D(x)^2 + D(x)D^2(x)D(x) \\ & + D(x)^2D^2(x))uD(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, z \in R. \end{aligned}$$

From (73) and (75), we have

$$(76) \quad D^2(x)D(x)^2uD(x)^2wf(z)D(z)f(z) = 0, \quad x, z, u, w \in R.$$

And, putting $wf(z)D(z)f(z)uD^2(x)$ instead of u in (76), it follows that obtain

$$(77) \quad D^2(x)D(x)^2wf(z)D(z)f(z)uD^2(x)D(x)^2wf(z)D(z)f(z) = 0, \quad u, w, x, z \in R.$$

Since R is semiprime, we get

$$(78) \quad D^2(x)D(x)^2wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Replacing $x + ty$ for x in (78), we have

$$(79) \quad \begin{aligned} & D^2(x + ty)D(x + ty)^2wf(z)D(z)f(z) \\ & \equiv D^2(x)D(x)^2wf(z)D(z)f(z) \\ & \quad + t\{(D^2(y)D(x)^2 + D^2(x)D(y)D(x) \\ & \quad + D^2(x)D(x)D(y))wf(z)D(z)f(z)\} \\ & \quad + t^2L(x, y)wf(z)D(z)f(z) \\ & \quad + t^3D^2(y)D(y)^2wf(z)D(z)f(z) = 0, \quad x, y, z, w \in R, \quad t \in S_3 \end{aligned}$$

where $L(x, y)$ denotes the term satisfying the identity (79).

From (78) and (79), we obtain

$$(80) \quad \begin{aligned} & t\{(D^2(y)D(x)^2 + D^2(x)D(y)D(x) \\ & \quad + D^2(x)D(x)D(y))wf(z)D(z)f(z)\} \\ & \quad + t^2L(x, y) = 0, \quad x, y, z, w \in R, \quad t \in S_3. \end{aligned}$$

Since R is $2!$ -torsion-free by assumption, by Lemma 2.1 the relation (80) yields

$$(81) \quad \begin{aligned} & (D^2(y)D(x)^2 + D^2(x)D(y)D(x) \\ & \quad + D^2(x)D(x)D(y))wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R \end{aligned}$$

Substituting yx for y in (81), it follows that

$$\begin{aligned} & (D^2(y)x D(x)^2 + 2D(y)D(x)^3 + yD^2(x)D(x)^2 \\ & \quad + D^2(x)D(y)x D(x) + D^2(x)y D(x)^2 \end{aligned}$$

$$(82) \quad \begin{aligned} & +D^2(x)D(x)D(y)x + D^2(x)D(x)yD(x))wf(z)D(z)f(z) \\ & = 0, \quad w, x, y, z \in R. \end{aligned}$$

Writing xw for w in (81), we get

$$(83) \quad \begin{aligned} & (D^2(y)D(x)^2x + D^2(x)D(y)D(x)x \\ & + D^2(x)D(x)D(y)x)wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Combining (50), (82) with (83), we have

$$(84) \quad \begin{aligned} & (-D^2(y)(f(x)D(x) + D(x)f(x)) - D^2(x)D(y)f(x) \\ & + D^2(x)yD(x)^2 + D^2(x)D(x)yD(x))wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Replacing $D(x)w$ for w in (84), we obtain

$$(85) \quad \begin{aligned} & (-D^2(y)(f(x)D(x)^2 + D(x)f(x)D(x)) - D^2(x)D(y)f(x)D(x) \\ & + D^2(x)yD(x)^3 + D^2(x)D(x)yD(x)^2)wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Combining (50), (57), (61) with (85), we have

$$(86) \quad \begin{aligned} & (-D^2(x)D(y)f(x)D(x) + D^2(x)D(x)yD(x)^2)wf(z)D(z)f(z) \\ & = 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting xy for y in (53), we obtain

$$(87) \quad \begin{aligned} & (xD(y)D(x)^2 + D(x)yD(x)^2 + D(x)xD(y)D(x) \\ & + D(x)^2yD(x) + D(x)^2xD(y) + D(x)^3y)wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Left multiplication of (53) by x gives

$$(88) \quad \begin{aligned} & (xD(y)D(x)^2 + xD(x)D(y)D(x) \\ & + xD(x)^2D(y))wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Combining (50), (87) with (88), we obtain

$$(89) \quad \begin{aligned} & (D(x)yD(x)^2 + f(x)D(y)D(x) \\ & + D(x)^2yD(x) + (f(x)D(x) + D(x)f(x))D(y))wf(z)D(z)f(z) \\ & = 0, \quad w, x, y, z \in R. \end{aligned}$$

Putting yx instead of y in (89), we have

$$(90) \quad \begin{aligned} & (D(x)yxD(x)^2 + f(x)D(y)xD(x) + f(x)yD(x)^2 \\ & + D(x)^2yxD(x) + (f(x)D(x) + D(x)f(x))D(y)x \\ & + (f(x)D(x) + D(x)f(x))yD(x))wf(z)D(z)f(z) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting xw for w in (89), we have

$$\begin{aligned}
 & (D(x)yD(x)^2x + f(x)D(y)D(x)x \\
 & + D(x)^2yD(x)^2x + (f(x)D(x) + D(x)f(x))D(y)x)wf(z)D(z)f(z) \\
 (91) \quad & = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

From (90) and (91), we get

$$\begin{aligned}
 & (-D(x)y(f(x)D(x) + D(x)f(x)) - f(x)D(y)f(x) + f(x)yD(x)^2 \\
 & - D(x)^2yf(x) + (f(x)D(x) + D(x)f(x))yD(x))wf(z)D(z)f(z) \\
 (92) \quad & = 0, \quad x, y, z, w \in R.
 \end{aligned}$$

Let $y = x$ in (92). Then we have

$$\begin{aligned}
 & (-D(x)x(f(x)D(x) + D(x)f(x)) - f(x)D(x)f(x) + f(x)xD(x)^2 \\
 & - D(x)^2xf(x) + (f(x)D(x) + D(x)f(x))xD(x))wf(z)D(z)f(z) \\
 (93) \quad & = 0, \quad w, x, z \in R.
 \end{aligned}$$

Using (1), (57) and (61), the relation (93) can be written as

$$\begin{aligned}
 & (-f(x)^2D(x) - 3f(x)D(x)f(x) + g(x)D(x)^2 + D(x)^2g(x) \\
 & + D(x)f(x)^2)wf(z)D(z)f(z) \\
 & = -2f(x)^2D(x) - 5f(x)D(x)f(x) - 2D(x)f(x)^2)wf(z)D(z)f(z) \\
 & = 0, \quad w, x, z \in R.
 \end{aligned}$$

Hence the above relation gives

$$(94) \quad (2f(x)^2D(x) + 5f(x)D(x)f(x) + 2D(x)f(x)^2)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

From (5) and (94), we get

$$(95) \quad (2f(x)^2D(x) - D(x)f(x)^2)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Comparing (5) and (95), we have

$$(96) \quad (5f(x)D(x)f(x) + 6f(x)^2D(x))wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Writing $f(x)w$ for w in (96), it follows that

$$(97) \quad (5f(x)D(x)f(x)^2 + 6f(x)^2D(x)f(x))wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Replacing $f(x)w$ for w in (64), we obtain

$$\begin{aligned}
 & (g(x)D(x)^2f(x) + f(x)^2D(x)f(x) + f(x)D(x)f(x)^2)wf(z)D(z)f(z) \\
 (98) \quad & = 0, \quad w, x, z \in R.
 \end{aligned}$$

From (1) and (98), we have

$$(99) \quad (f(x)^2 D(x)f(x) + f(x)D(x)f(x)^2)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Subtracting $5 \times (99)$ from (97), we get

$$(100) \quad f(x)^2 D(x)f(x)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

From (99) and (100), we have

$$(101) \quad f(x)D(x)f(x)^2 wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Writing $f(x)w$ for w in (95), it follows that

$$(102) \quad (2f(x)^2 D(x)f(x) - D(x)f(x)^3)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

From (100) and (102), we obtain

$$(103) \quad D(x)f(x)^3 wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Right multiplication of (103) by $5f(z)$ gives

$$(104) \quad D(x)f(x)^3 w(5f(z)D(z)f(z)^2) = 0, \quad w, x, z \in R.$$

From (5) and (104), we obtain

$$(105) \quad D(x)f(x)^3 w(-3D(z)f(z)^3) = 0, \quad w, x, z \in R.$$

Thus since R is 3!-torsion-free, setting $z = x$ in (105) we have

$$(106) \quad D(x)f(x)^3 wD(x)f(x)^3 = 0, \quad w, x \in R.$$

Since R is semiprime, it follows from (106) that

$$(107) \quad D(x)f(x)^3 = 0, \quad x \in R.$$

Left multiplication of (95) by $f(x)$ gives

$$(108) \quad (2f(x)^3 D(x) - f(x)D(x)f(x)^2)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Combining (101) with (108), we obtain

$$(109) \quad 2f(x)^3 D(x)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Since R is 2!-torsion-free, we get from (109)

$$(110) \quad f(x)^3 D(x)wf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Writing xw for w in (110), we obtain

$$(111) \quad f(x)^3 D(x)xwf(z)D(z)f(z) = 0, \quad w, x, z \in R.$$

Left multiplication of (110) by x gives

$$(112) \quad xf(x)^3D(x)wf(z)D(z)f(z) = 0, w, x, z \in R.$$

Combining (111) with (112), we obtain

$$(113) \quad (g(x)f(x)^2D(x) + f(x)g(x)f(x)D(x) + f(x)^2g(x)D(x) + f(x)^4)wf(z)D(z)f(z) = 0, w, x, z \in R.$$

Writing $f(x)^3w$ for w in (113), we obtain

$$(114) \quad (g(x)f(x)^2D(x)f(x)^3 + f(x)g(x)f(x)D(x)f(x)^3 + f(x)^2g(x)D(x)f(x)^3 + f(x)^7)wf(z)D(z)f(z) = 0, w, x, z \in R.$$

Combining (107) with (114), we obtain

$$(115) \quad f(x)^7wf(z)D(z)f(z) = 0, w, x, z \in R.$$

Right multiplication of (115) by z gives

$$(116) \quad f(x)^7wf(z)D(z)f(z)z = 0, w, x, z \in R.$$

Writing wz for w in (115), it follows that

$$(117) \quad f(x)^7wzf(z)D(z)f(z) = 0, w, x, z \in R.$$

Combining (116) with (117), we get

$$(118) \quad f(x)^7w[f(z)D(z)f(z), z] = f(x)^7w(g(z)D(z)f(z) + f(z)^3 + f(z)D(z)g(z)) = 0, w, x, z \in R.$$

On the other hand, replacing $y + tz$ for z in (103), we have

$$(119) \quad \begin{aligned} & f(x)^7wf(y + tz)D(y + tz)f(y + tz) \\ \equiv & f(x)^7wf(y)D(y)f(y) \\ & + t\{f(x)^7w(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(y)B(y, z))\} \\ & + t^2f(x)^7wM_1(y, z) + t^3f(x)^7wM_2(y, z) + t^4f(x)^7wM_4(y, z) \\ & + t^5f(x)^7wf(z)D(z)f(z) = 0, w, x, y, z \in R, t \in S_3 \end{aligned}$$

where $M_i(y, z)$, $1 \leq i \leq 4$, denotes the term satisfying the identity (119).

From (103) and (119), we obtain

$$\begin{aligned} & t\{f(x)^7w(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(z)B(y, z))\} \\ & + t^2f(x)^7wM_1(y, z) + t^3f(x)^7wM_2(y, z) + t^4f(x)^7wM_4(y, z) \\ (120) \quad & = 0, \quad w, x, y, z \in R, \quad t \in S_4. \end{aligned}$$

Since R is 4!-torsion-free by assumption, by Lemma 2.1 the relation (120) yields

$$\begin{aligned} & f(x)^7w(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(y)B(y, z)) \\ (121) \quad & = 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting y^2 for z in (121), we obtain

$$\begin{aligned} & f(x)^7w(3f(y)yD(y)f(y) + 2yf(y)D(y)f(y) + 2f(y)D(y)f(y)y \\ (122) \quad & + 3f(y)D(y)yf(y)) = 0, \quad w, x, y \in R. \end{aligned}$$

Combining (115) with (122), using (113) we have

$$(123) \quad f(x)^7w(3(g(y)D(y)f(y) - f(y)D(y)g(y))) = 0, \quad w, x, y \in R.$$

Since R is 3!-torsion-free, we get (123)

$$(124) \quad f(x)^7w(g(y)D(y)f(y) - f(y)D(y)g(y)) = 0, \quad w, x, y \in R.$$

Combining (118) with (124), we obtain

$$(125) \quad f(x)^7w(2g(z)D(z)f(z) + f(z)^3) = 0, \quad w, x, z \in R.$$

Right multiplication of (125) by $f(z)^4$ gives

$$(126) \quad f(x)^7w(2g(z)D(z)f(z)^5 + f(z)^7) = 0, \quad w, x, z \in R.$$

Combining (107) with (126), and setting $z = x$ in (126) we obtain

$$(127) \quad f(x)^7wf(x)^7 = 0, \quad w, x \in R.$$

Since R is semiprime, we obtain from (127)

$$f(x)^7 = 0, \quad x \in R.$$

□

Theorem 2.5. *Let R be a 7!-torsion free noncommutative semiprime ring. Suppose there exists a Jordan derivation $D : R \rightarrow R$ such that*

$$[D(x), x]D(x)^2 = 0$$

for all $x \in R$. In this case we have $[D(x), x]^7 = 0$ for all $x \in R$.

Proof. By Theorem 2.2, we can see that D is a derivation on R . For simplicity, we shall denote the maps $B : R \times R \rightarrow R$, $f, g : R \rightarrow R$ by $B(x, y) \equiv [D(x), y] + [D(y), x]$, $f(x) \equiv [D(x), x]$, $g(x) \equiv [f(x), x]$ for all $x, y \in R$ respectively. Then we have the basic properties:

$$\begin{aligned} B(x, y) &= B(y, x), \quad B(x, yz) = B(x, y)z + yB(x, z) + D(y)[z, x] + [y, x]D(z), \\ B(x, x) &= 2f(x), \quad B(xy, z) = B(y, z)x + zB(y, x) + D(z)[x, y] + [z, y]D(x), \\ B(x, x^2) &= 2(f(x)x + xf(x)), \quad x, y, z \in R. \end{aligned}$$

After this, we use the above relations without specific reference. By assumption,

$$(128) \quad f(x)D(x)^2 = 0, \quad x \in R$$

Replacing $x + ty$ for x in (128), we have

$$\begin{aligned} & f(x + ty)D(x + ty)^2 \\ & \equiv f(x)D(x)^2 + t\{B(x, y)D(x)^2 + f(x)D(y)D(x) + f(x)D(x)D(y)\} \\ & \quad + t^2N_1(x, y) + t^3N_2(x, y) + t^4f(y)D(y)^2 \\ (129) \quad & = 0, \quad x, y \in R, \quad t \in S_3 \end{aligned}$$

where N_i , $1 \leq i \leq 2$, denotes the term satisfying the identity (129).

From (128) and (129), we obtain

$$(130) \quad \begin{aligned} & t\{B(x, y)D(x)^2 + f(x)D(y)D(x) + f(x)D(x)D(y)\} \\ & + t^2N_1(x, y) + t^3N_2(x, y) = 0, \quad x, y \in R, \quad t \in S_3 \end{aligned}$$

Since R is 3!-torsion free by assumption, by Lemma 2.1 the relation (130) yields

$$(131) \quad B(x, y)D(x)^2 + f(x)D(y)D(x) + f(x)D(x)D(y) = 0, \quad x, y \in R.$$

Let $y = x^2$ in (131). Then using (128), we have

$$\begin{aligned} & 2(f(x)x + xf(x))D(x)^2 + f(x)(D(x)x + xD(x))D(x) \\ & + f(x)D(x)(D(x)x + xD(x)) \\ & = -2f(x)(f(x)D(x) + D(x)f(x)) - f(x)D(x)f(x) \\ & \quad - f(x)(f(x)D(x) + D(x)f(x)) - f(x)D(x)f(x) \\ & = -3f(x)^2D(x) - 5f(x)D(x)f(x) = 0, \quad x \in R. \end{aligned}$$

Thus the above relation gives

$$(132) \quad 3f(x)^2D(x) + 5f(x)D(x)f(x) = 0, \quad x \in R.$$

Using (128), we arrive at

$$(133) \quad \begin{aligned} 0 &= [f(x)D(x)^2, x] \\ &= g(x)D(x)^2 + f(x)^2D(x) + f(x)D(x)f(x), \quad x \in R. \end{aligned}$$

From (132) and (133), we get

$$(134) \quad 2f(x)D(x)f(x) - 3g(x)D(x)^2 = 0, \quad x \in R.$$

Combining (132) with (134),

$$3(2f(x)^2D(x) + 5g(x)D(x)^2) = 0, \quad x \in R.$$

Since R is $3!$ -torsion-free, the above relation gives

$$(135) \quad 2f(x)^2D(x) + 5g(x)D(x)^2 = 0, \quad x \in R.$$

Right multiplication of (135) by $D(x)$ leads to

$$(136) \quad 2f(x)^2D(x)^2 + 5g(x)D(x)^3 = 0, \quad x \in R.$$

Comparing (128) and (136), we arrive at

$$(137) \quad 5g(x)D(x)^3 = 0, \quad x \in R.$$

Since R is $5!$ -torsion-free, (137) gives

$$(138) \quad g(x)D(x)^3 = 0, \quad x \in R.$$

Writing yx for y in (131), we get

$$(139) \quad \begin{aligned} &(B(x, y)x + 2yf(x) + [y, x]D(x))D(x)^2 + f(x)(D(y)x + yD(x))D(x) \\ &f(x)D(x)(D(y)x + yD(x)) = 0, \quad x, y \in R. \end{aligned}$$

Right multiplication of (131) by x leads to

$$(140) \quad B(x, y)D(x)^2x + f(x)D(y)D(x)x + f(x)D(x)D(y)x = 0, \quad x, y \in R.$$

From (139) and (140), we arrive at

$$(141) \quad \begin{aligned} &-B(x, y)(f(x)D(x) + D(x)f(x)) + 2yf(x)D(x)^2 + [y, x]D(x)^3 \\ &-f(x)D(y)f(x) + f(x)yD(x)^2 + f(x)D(x)yD(x) \\ &= 0, \quad x, y \in R. \end{aligned}$$

By (128) and (141), it follows that

$$(142) \quad \begin{aligned} &-B(x, y)(f(x)D(x) + D(x)f(x)) + [y, x]D(x)^3 \\ &-f(x)D(y)f(x) + f(x)yD(x)^2 + f(x)D(x)yD(x) = 0, \quad x, y \in R. \end{aligned}$$

Replacing xy for y in (142), it follows from that

$$(143) \quad \begin{aligned} & -(xB(x, y) + 2f(x)y + D(x)[y, x])(f(x)D(x) + D(x)f(x)) + x[y, x]D(x)^3 \\ & -f(x)(xD(y) + D(x)y)f(x) + f(x)xyD(x)^2 + f(x)D(x)xyD(x) \\ & = 0, \quad x, y \in R. \end{aligned}$$

Left multiplication of (142) by x leads to

$$(144) \quad \begin{aligned} & -xB(x, y)(f(x)D(x) + D(x)f(x)) + x[y, x]D(x)^3 \\ & -xf(x)D(y)f(x) + xf(x)yD(x)^2 + xf(x)D(x)yD(x) = 0, \quad x, y \in R. \end{aligned}$$

Comparing (143) and (144), we see that

$$(145) \quad \begin{aligned} & -2f(x)y(f(x)D(x) + D(x)f(x)) - D(x)[y, x](f(x)D(x) + D(x)f(x)) \\ & -g(x)D(y)f(x) - f(x)D(x)yf(x) + g(x)yD(x)^2 \\ & +(g(x)D(x) + f(x)^2)yD(x) = 0, \quad x, y \in R. \end{aligned}$$

Right multiplication of (145) by $D(x)^2$ leads to

$$(146) \quad \begin{aligned} & -2f(x)y(f(x)D(x)^3 + D(x)f(x)D(x)^2) \\ & -D(x)[y, x](f(x)D(x)^3 + D(x)f(x)D(x)^2) \\ & -g(x)D(y)f(x)D(x)^2 - f(x)D(x)yf(x)D(x)^2 + g(x)yD(x)^4 \\ & +(g(x)D(x) + f(x)^2)yD(x)^3 = 0, \quad x, y \in R. \end{aligned}$$

Combining (128) with (146), we get

$$(147) \quad g(x)yD(x)^4 + (g(x)D(x) + f(x)^2)yD(x)^3 = 0, \quad x, y \in R.$$

Replacing $D(x)^2y$ for y in (147), we have

$$(148) \quad g(x)D(x)^2yD(x)^4 + (g(x)D(x)^3 + f(x)^2D(x)^2)yD(x)^3 = 0, \quad x, y \in R.$$

From (128),(138) and (148), it is obvious that

$$(149) \quad g(x)D(x)^2yD(x)^4 = 0, \quad x, y \in R.$$

Using (135), it follows from (149) that

$$(150) \quad 2f(x)^2D(x)yD(x)^4 = -5g(x)D(x)^2yD(x)^4 = 0, \quad x, y \in R.$$

Thus since R is 2-torsion-free, (150) gives

$$(151) \quad f(x)^2D(x)yD(x)^4 = 0, \quad x, y \in R.$$

From (134) and (151), we have

$$(152) \quad 2f(x)D(x)f(x)yD(x)^4 = 3g(x)D(x)^2yD(x)^4 = 0, \quad x, y \in R.$$

And so, since R is 2-torsion-free, (152) yields

$$(153) \quad f(x)D(x)f(x)yD(x)^4 = 0, \quad x, y \in R.$$

Substituting $zf(x)D(x)f(x)y$ for y in (147), we have

$$(154) \quad \begin{aligned} &g(x)zf(x)D(x)f(x)yD(x)^4 + (g(x)D(x) \\ &+ f(x)^2)zf(x)D(x)f(x)yD(x)^3 = 0, \quad x, y, z \in R. \end{aligned}$$

From (153) and (154), we obtain

$$(155) \quad (g(x)D(x) + f(x)^2)zf(x)D(x)f(x)yD(x)^3 = 0, \quad x, y, z \in R.$$

Putting $D(x)z$ instead of z in (155), we get

$$(156) \quad (g(x)D(x)^2 + f(x)^2D(x))zf(x)D(x)f(x)yD(x)^3 = 0, \quad x, y, z \in R.$$

Using (133), the relation (156) gives

$$(157) \quad \begin{aligned} &f(x)D(x)f(x)zf(x)D(x)f(x)yD(x)^3 \\ &= -(g(x)D(x)^2 + f(x)^2D(x))zf(x)D(x)f(x)yD(x)^3 = 0, \quad x, y, z \in R. \end{aligned}$$

Writing $yD(x)^3z$ for z in (157),

$$(158) \quad \begin{aligned} &f(x)D(x)f(x)yD(x)^3zf(x)D(x)f(x)yD(x)^3 \\ &= 0, \quad x, y, z \in R. \end{aligned}$$

Since R is semiprime, we have from (158)

$$(159) \quad f(x)D(x)f(x)yD(x)^3 = 0, \quad x, y \in R.$$

Replacing $x + tz$ for x in (159), we have

$$(160) \quad \begin{aligned} &f(x + tz)D(x + tz)f(x + tz)yD(x + tz)^3 \\ &\equiv f(x)D(x)f(x)yD(x)^3 \\ &+ t\{(B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z))yD(x)^3 \\ &+ f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))\} \\ &+ t^2P_1(x, y, z) + t^3P_2(x, y, z) + t^4P_3(x, y, z) \\ &+ t^5P_4(x, y, z) + t^6P_5(x, y, z) + t^7P_6(x, y, z) \\ &+ t^8f(z)D(z)f(z)yD(z)^3 = 0, \quad x, y, z \in R, \quad t \in S_7 \end{aligned}$$

where $P_i, 1 \leq i \leq 6$, denotes the term satisfying the identity (160).

From (159) and (160), we obtain

$$\begin{aligned}
 & t\{(B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z))yD(x)^3 \\
 & + f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))\} \\
 & + t^2P_1(x, y, z) + t^3P_2(x, y, z) + t^4P_3(x, y, z) \\
 & + t^5P_4(x, y, z) + t^6P_5(x, y, z) + t^7P_6(x, y, z) \\
 (161) \quad & = 0, \quad x, y, z \in R, \quad t \in S_7.
 \end{aligned}$$

Since R is 7!-torsion-free by assumption, by Lemma 2.1 the relation (161) yields

$$\begin{aligned}
 & (B(x, z)D(x)f(x) + f(x)D(z)f(x) + f(x)D(x)B(x, z))yD(x)^3 \\
 & + f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z)) \\
 (162) \quad & = 0, \quad x, y, z \in R.
 \end{aligned}$$

Substituting $wf(x)D(x)f(x)y$ for y in (162), we obtain

$$\begin{aligned}
 & (B(x, z)D(x)f(x) + f(x)D(z)f(x) \\
 & + f(x)D(x)B(x, z))wf(x)D(x)f(x)yD(x)^3 \\
 & + f(x)D(x)f(x)wf(x)D(x)f(x)y(D(z)D(x)^2 \\
 (163) \quad & + D(x)D(z)D(x) + D(x)^2D(z)) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Combining (159) with (163), we get

$$\begin{aligned}
 & f(x)D(x)f(x)wf(x)D(x)f(x)y(D(z)D(x)^2 \\
 (164) \quad & + D(x)D(z)D(x) + D(x)^2D(z)) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Writing $y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))w$ for w in (164), we obtain

$$\begin{aligned}
 & f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) \\
 & + D(x)^2D(z))wf(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) \\
 (165) \quad & + D(x)^2D(z)) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Since R is semiprime, it follows from (165) that

$$(166) \quad f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z)) = 0, \quad x, y, z \in R.$$

Replacing $x + tu$ for x in (166), we have

$$\begin{aligned}
 & f(x + tu)D(x + tu)f(x + tu)y(D(z)D(x + tu)^2 \\
 & + D(x + tu)D(z)D(x + tu) + D(x + tu)^2D(z)) \\
 \equiv & f(x)D(x)f(x)y(D(z)D(x)^2 + D(x)D(z)D(x) + D(x)^2D(z))
 \end{aligned}$$

$$\begin{aligned}
& +t\{f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
& +D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) + (B(x,u)D(x)f(x) \\
& +f(x)D(u)f(x) + f(x)D(x)B(x,u))y(D(z)D(x)^2 \\
& +D(x)D(z)D(x) + D(x)^2D(z))\} \\
& +t^2Q_1(x,y,z,u) + t^3JQ_2(x,y,z,u) + t^4Q_3(x,y,z,u) \\
& +t^5Q_4(x,y,z,u) + t^6Q_5(x,y,z,u) \\
& +t^7f(u)D(u)f(u)y(D(z)D(u)^2 + D(u)D(z)D(u) \\
(167) \quad & +D(u)^2D(z)) = 0, \quad u, x, y, z \in R, \quad t \in S_6
\end{aligned}$$

where Q_i , $1 \leq i \leq 5$, denotes the term satisfying the identity (167).

From (166) and (167), we obtain

$$\begin{aligned}
& t\{f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
& +D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) + (B(x,u)D(x)f(x) \\
& +f(x)D(u)f(x) + f(x)D(x)B(x,u))y(D(z)D(x)^2 + D(x)D(z)D(x) \\
& +D(x)^2D(z))\} + t^2Q_1(x,y,z,u) + t^3JQ_2(x,y,z,u) + t^4Q_3(x,y,z,u) \\
(168) \quad & +t^5Q_4(x,y,z,u) + t^6Q_5(x,y,z,u) = 0, \quad u, x, y, z \in R, \quad t \in S_6.
\end{aligned}$$

Since R is 6!-torsion-free by assumption, by Lemma 2.1 the relation (168) yields

$$\begin{aligned}
& f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\
& +D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) + (B(x,u)D(x)f(x) \\
& +f(x)D(u)f(x) + f(x)D(x)B(x,u))y(D(z)D(x)^2 \\
(169) \quad & +D(x)D(z)D(x) + D(x)^2D(z)) = 0, \quad u, x, y, z \in R.
\end{aligned}$$

Substituting $wf(x)D(x)f(x)y$ for y in (169), we obtain

$$\begin{aligned}
& f(x)D(x)f(x)wf(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) \\
& +D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) \\
& +(B(x,u)D(x)f(x) + f(x)D(u)f(x) \\
& +f(x)D(x)B(x,u))wf(x)D(x)f(x)y(D(z)D(x)^2 \\
(170) \quad & +D(x)D(z)D(x) + D(x)^2D(z)) = 0, \quad x, y, z, u \in R.
\end{aligned}$$

Combining (166) with (170), we get

$$f(x)D(x)f(x)wf(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u))$$

$$(171) \quad \begin{aligned} &+D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) \\ &= 0, u, x, y, z \in R. \end{aligned}$$

Putting $y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z))w$ instead of w in (171), we obtain

$$(172) \quad \begin{aligned} &f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\ &+D(x)D(z)D(u) + (D(u)D(x) \\ &+D(x)D(u))D(z))wf(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) \\ &+D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) \\ &= 0, u, w, x, y, z \in R. \end{aligned}$$

Since R is semiprime, it follows from (172) that

$$(173) \quad \begin{aligned} &f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\ &+D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) = 0, u, w, x, y, z \in R. \end{aligned}$$

Starting from (173), we have

$$(174) \quad \begin{aligned} &f(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) + D(u)D(z)D(x) \\ &+D(x)D(z)D(u) + (D(u)D(x) \\ &+D(x)D(u))D(z))wf(x)D(x)f(x)y(D(z)(D(u)D(x) + D(x)D(u)) \\ &+D(u)D(z)D(x) + D(x)D(z)D(u) + (D(u)D(x) + D(x)D(u))D(z)) \\ &= 0, u, v, w, x, y, z \in R. \end{aligned}$$

in the same fashion that makes it possible to obtain (173) from (166).

And so, setting $v = u = z$ in (174), the relation (174) yields

$$6f(x)D(x)f(x)yD(z)^3 = 0, x, y, z \in R.$$

Since R is 3!-torsion-free, replacing x, z, w for z, x, y in the above relation, it is obvious that

$$(175) \quad f(z)D(z)f(z)wD(x)^3 = 0, x, z, w \in R.$$

Replacing $x + ty$ for x in (175), we have

$$\begin{aligned} &f(z)D(z)f(z)wD(x + ty)^3 \\ &\equiv f(z)D(z)f(z)wD(x)^3 + t\{f(z)D(z)f(z)w(D(y)D(x))^2 \\ &+D(x)D(y)D(x) + D(x)^2D(y)\} \end{aligned}$$

$$(176) \quad \begin{aligned} & +t^2 f(z)D(z)f(z)wS(x, y) + t^3 f(z)D(z)f(z)wD(y)^3 \\ & = 0, \quad w, x, y, z \in R, \quad t \in S_2 \end{aligned}$$

where $S(x, y)$ denotes the term satisfying the identity (176).

From (175) and (176), we obtain

$$(177) \quad \begin{aligned} & t\{f(z)D(z)f(z)w(D(y)D(x)^2 + D(x)D(y)D(x) + D(x)^2D(y))\} \\ & +t^2 f(z)D(z)f(z)wS(x, y) = 0, \quad w, x, y, z \in R, \quad t \in S_3 \end{aligned}$$

Since R is 2!-torsion-free by assumption, by Lemma 2.1 the relation (177) yields

$$(178) \quad \begin{aligned} & f(z)D(z)f(z)w(D(y)D(x)^2 + D(x)D(y)D(x) + D(x)^2D(y)) \\ & = 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting x^2 for y in (178), we obtain

$$(179) \quad \begin{aligned} & f(z)D(z)f(z)w(D(x)xD(x)^2 + xD(x)^3 + D(x)(D(x)x + xD(x))D(x) \\ & +D(x)^2(D(x)x + xD(x))) = 0, \quad w, x, z \in R. \end{aligned}$$

Combining (175) with (179), we get

$$(180) \quad 2f(z)D(z)f(z)w(f(x)D(x)^2 - D(x)^2f(x)) = 0, \quad w, x, z \in R.$$

Since R is 2!-torsion-free by assumption, the relation (180) yields

$$(181) \quad f(z)D(z)f(z)w(f(x)D(x)^2 - D(x)^2f(x)) = 0, \quad w, x, z \in R.$$

From (128) and (181), we have

$$(182) \quad f(z)D(z)f(z)wD(x)^2f(x) = 0, \quad w, x, z \in R.$$

On the other hand, substituting wx for w in (175), we obtain

$$(183) \quad f(z)D(z)f(z)wxD(x)^3 = 0, \quad w, x, z \in R.$$

Right multiplication of (175) by x gives

$$(184) \quad f(z)D(z)f(z)wD(x)^3x = 0, \quad w, x, z \in R.$$

Combining (183) with (184), we get

$$(185) \quad \begin{aligned} & f(z)D(z)f(z)w[D(x)^3, x] \\ & = f(z)D(z)f(z)w(f(x)D(x)^2 \\ & +D(x)f(x)D(x) + D(x)^2f(x)) = 0, \quad w, x, z \in R. \end{aligned}$$

From (128), (182) and (185), it is obvious that

$$(186) \quad f(z)D(z)f(z)wD(x)f(x)D(x) = 0, \quad w, x, z \in R.$$

Writing wx for w in (182), we obtain

$$(187) \quad f(z)D(z)f(z)wxD(x)^2f(x) = 0, \quad w, x, z \in R.$$

Right multiplication of (182) by x gives

$$(188) \quad f(z)D(z)f(z)wD(x)^2f(x)x = 0, \quad w, x, z \in R.$$

Combining (187) with (188), we get

$$(189) \quad \begin{aligned} & f(z)D(z)f(z)w[D(x)^2f(x), x] \\ &= f(z)D(z)f(z)w(f(x)D(x)f(x) \\ &+ D(x)f(x)^2 + D(x)^2g(x)) = 0, \quad w, x, z \in R. \end{aligned}$$

Right multiplication of (178) by $D(x)^2$ gives

$$(190) \quad \begin{aligned} & f(z)D(z)f(z)w(D(y)D(x)^4 \\ &+ D(x)D(y)D(x)^3 + D(x)^2D(y)D(x)^2) = 0, \quad w, x, y, z \in R. \end{aligned}$$

From (175) and (190), we obtain

$$(191) \quad f(z)D(z)f(z)wD(x)^2D(y)D(x)^2 = 0, \quad w, x, y, z \in R.$$

Putting $uD(x)^2y$ instead of y in (191), we have

$$(192) \quad \begin{aligned} & f(z)D(z)f(z)w(D(x)^2(D(y)D(x)^2uD(x)^2 \\ &+ D(x)^2yD(D(x)^2)uD(x)^2 + D(x)^2yD(x)^2D(u)D(x)^2) \\ &= 0, \quad u, w, x, y, z, w \in R. \end{aligned}$$

Comparing (191) and (192), we get

$$(193) \quad f(z)D(z)f(z)wD(x)^2yD(D(x)^2)uD(x)^2 = 0, \quad u, w, x, y, z \in R.$$

Substituting $vf(z)D(z)f(z)w$ for u in (193), we obtain

$$(194) \quad f(z)D(z)f(z)wD(x)^2yD(D(x)^2)vf(z)D(z)f(z)wD(x)^2 = 0, \quad v, w, x, y, z \in R.$$

Right multiplication of (194) by $yD(D(x)^2)$ gives

$$(195) \quad \begin{aligned} & f(z)D(z)f(z)wD(x)^2yD(D(x)^2)vf(z)D(z)f(z)wD(x)^2yD(D(x)^2) \\ &= 0, \quad v, w, x, y, z \in R. \end{aligned}$$

Since R is semiprime, the relation (195) yields

$$(196) \quad f(z)D(z)f(z)wD(x)^2yD(D(x)^2) = 0, \quad w, x, y, z \in R.$$

The relation (196) yields

$$(197) \quad f(z)D(z)f(z)wD(x)^2y(D^2(x)D(x) + D(x)D^2(x)) = 0, \quad w, x, y, z \in R.$$

Right multiplication of (197) by $D(x)$ gives

$$(198) \quad f(z)D(z)f(z)wD(x)^2y(D^2(x)D(x)^2 + D(x)D^2(x)D(x)) = 0, \quad w, x, y, z \in R.$$

Substituting $D(x)$ for y in (178), we obtain

$$(199) \quad \begin{aligned} & f(z)D(z)f(z)w(D^2(x)D(x)^2 + D(x)D^2(x)D(x)) \\ & + D(x)^2D^2(x) = 0, \quad w, x, y, z \in R. \end{aligned}$$

Substituting $wD(x)^2y$ for w in (199), we obtain

$$(200) \quad \begin{aligned} & f(z)D(z)f(z)wD(x)^2y(D^2(x)D(x)^2 + D(x)D^2(x)D(x)) \\ & + D(x)^2D^2(x) = 0, \quad w, x, y, z \in R. \end{aligned}$$

From (198) and (200), we have

$$(201) \quad f(z)D(z)f(z)wD(x)^2yD(x)^2D^2(x) = 0, \quad x, y, z, w \in R.$$

And, substituting $D^2(x)yf(z)D(z)f(z)w$ for y in (201), we obtain

$$(202) \quad \begin{aligned} & f(z)D(z)f(z)wD(x)^2D^2(x)yf(z)D(z)f(z)wD(x)^2D^2(x) \\ & = 0, \quad x, y, z, w \in R. \end{aligned}$$

Since R is semiprime, we get from (202)

$$(203) \quad f(z)D(z)f(z)wD(x)^2D^2(x) = 0, \quad w, x, y, z \in R.$$

Replacing $x + ty$ for x in (203), we have

$$(204) \quad \begin{aligned} & f(z)D(z)f(z)wD^2(x + ty)D(x + ty)^2 \\ \equiv & f(z)D(z)f(z)wD(x)^2D^2(x) \\ & + t\{f(z)D(z)f(z)w(D(y)D(x)D^2(x) + D(x)D(y)D^2(x) \\ & + D(x)^2D^2(y))\} \\ & + t^2f(z)D(z)f(z)wT(x, y) \\ & + t^3f(z)D(z)f(z)wD(y)^2D^2(y) = 0, \quad w, x, y, z \in R, \quad t \in S_3 \end{aligned}$$

where $T(x, y)$ denotes the term satisfying the identity (204).

From (203) and (204), we obtain

$$\begin{aligned}
 & t\{f(z)D(z)f(z)w(D(y)D(x)D^2(x) + D(x)D(y)D^2(x) \\
 & + D(x)^2D^2(y))\} \\
 & + t^2f(z)D(z)f(z)wT(x, y) \\
 (205) \quad & = 0, \quad w, x, y, z, w \in R, \quad t \in S_3.
 \end{aligned}$$

Since R is 2!-torsion-free by assumption, by Lemma 2.1 the relation (205) yields

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(y)D(x)D^2(x) + D(x)D(y)D^2(x) \\
 (206) \quad & + D(x)^2D^2(y)) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Substituting xy for y in (206), we obtain

$$\begin{aligned}
 & f(z)D(z)f(z)w(xD(y)D(x)D^2(x) + D(x)yD(x)D^2(x) \\
 & + D(x)xD(y)D^2(x) + D(x)^2yD^2(x) \\
 & + D(x)^2xD^2(y) + 2D(x)^3D(y) + D(x)^2D^2(x)y) \\
 (207) \quad & = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Writing wx for w in (206), we get

$$\begin{aligned}
 & f(z)D(z)f(z)w(xD(y)D(x)D^2(x) + xD(x)D(y)D^2(x) \\
 (208) \quad & + xD(x)^2D^2(y)) = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Combining (175), (203), (207) with (208), we have

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(x)yD(x)D^2(x) + f(x)D(y)D^2(x) \\
 & + D(x)^2yD^2(x) + (f(x)D(x) + D(x)f(x))D^2(y)) \\
 (209) \quad & = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Replacing $wD(x)$ for w in (209), we obtain

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(x)^2yD(x)D^2(x) + D(x)f(x)D(y)D^2(x) \\
 & + D(x)^3yD^2(x) + (D(x)f(x)D(x) + D(x)^2f(x))D^2(y)) \\
 (210) \quad & = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Comparing (175), (182), (186), (203) and (210), we have

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(x)^2yD(x)D^2(x) + D(x)f(x)D(y)D^2(x) \\
 (211) \quad & = 0, \quad w, x, y, z \in R.
 \end{aligned}$$

Substituting yx for y in (178), we obtain

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(y)xD(x)^2 + yD(x)^3 + D(x)D(y)xD(x) \\
 & + D(x)yD(x)^2 + D(x)^2yD(x) + D(x)^2D(y)x) \\
 (212) \quad & = 0, w, x, y, z \in R.
 \end{aligned}$$

Right multiplication of (178) by x gives

$$\begin{aligned}
 & f(z)D(z)f(z)w(D(y)D(x)^2x + D(x)D(y)D(x)x + D(x)^2D(y)x) \\
 (213) \quad & = 0, w, x, y, z \in R.
 \end{aligned}$$

Combining (175), (212) with (213), we obtain

$$\begin{aligned}
 & f(z)D(z)f(z)w(-D(y)(f(x)D(x) + D(x)f(x)) \\
 (214) \quad & -D(x)D(y)f(x) + D(x)yD(x)^2 + D(x)^2yD(x)) = 0, w, x, y, z \in R.
 \end{aligned}$$

Putting xy instead of y in (214), we have

$$\begin{aligned}
 & f(z)D(z)f(z)w(-xD(y)(f(x)D(x) + D(x)f(x)) \\
 & -D(x)y(f(x)D(x) + D(x)f(x))D(x)^2 - D(x)xD(y)f(x) - D(x)^2yf(x) \\
 (215) \quad & +D(x)xyD(x)^2 + D(x)^2xyD(x)) = 0, w, x, y, z \in R.
 \end{aligned}$$

Substituting wx for w in (214), we have

$$\begin{aligned}
 & f(z)D(z)f(z)w(-xD(y)(f(x)D(x) + D(x)f(x)) \\
 (216) \quad & -xD(x)D(y)f(x) + xD(x)yD(x)^2 + xD(x)^2yD(x)) = 0, w, x, y, z \in R.
 \end{aligned}$$

From (215) and (216), we get

$$\begin{aligned}
 & f(z)D(z)f(z)w(-D(x)y(f(x)D(x) + D(x)f(x)) - f(x)D(y)f(x) \\
 & -D(x)^2yf(x) + f(x)yD(x)^2 + (f(x)D(x) + D(x)f(x))yD(x)) \\
 (217) \quad & = 0, w, x, y, z \in R.
 \end{aligned}$$

Let $y = x$ in (217). Then we have

$$\begin{aligned}
 & f(z)D(z)f(z)w(-D(x)x(f(x)D(x) + D(x)f(x)) - f(x)D(x)f(x) \\
 & -D(x)^2xf(x) + f(x)xD(x)^2 + (f(x)D(x) + D(x)f(x))xD(x)) \\
 (218) \quad & = 0, w, x, z \in R.
 \end{aligned}$$

Using (186), (218) gives

$$\begin{aligned}
 & f(z)D(z)f(z)w(-f(x)(f(x)D(x) + D(x)f(x)) - f(x)D(x)f(x) \\
 & -(f(x)D(x) + D(x)f(x))f(x) + g(x)D(x)^2
 \end{aligned}$$

$$\begin{aligned}
 & -(f(x)D(x) + D(x)f(x))f(x) \\
 & = f(z)D(z)f(z)w(-f(x)^2D(x) - 4f(x)D(x)f(x) - D(x)f(x)^2 \\
 (219) \quad & +g(x)D(x)^2) = 0, \quad w, x, z \in R.
 \end{aligned}$$

Thus the relation (219) yields

$$\begin{aligned}
 & f(z)D(z)f(z)w(2f(x)^2D(x) + 5f(x)D(x)f(x) + 2D(x)f(x)^2) \\
 (220) \quad & = 0, \quad w, x, z \in R.
 \end{aligned}$$

From (132) and (220), we get

$$(221) \quad f(z)D(z)f(z)w(f(x)^2D(x) - 2D(x)f(x)^2) = 0, \quad w, x, z \in R.$$

According to (132) and (221), we have

$$(222) \quad f(z)D(z)f(z)w(5f(x)D(x)f(x) + 6D(x)f(x)^2) = 0, \quad w, x, z \in R.$$

Writing $wf(x)$ for w in (222), it follows that

$$(223) \quad f(z)D(z)f(z)w(5f(x)^2D(x)f(x) + 6f(x)D(x)f(x)^2) = 0, \quad w, x, z \in R.$$

Replacing $wf(x)$ for w in (189), we obtain

$$\begin{aligned}
 & f(z)D(z)f(z)w(f(x)^2D(x)f(x) + f(x)D(x)f(x)^2 + f(x)D(x)^2g(x)) \\
 (224) \quad & = 0, \quad w, x, z \in R.
 \end{aligned}$$

From (128) and (224), we have

$$(225) \quad f(z)D(z)f(z)w(f(x)^2D(x)f(x) + f(x)D(x)f(x)^2) = 0, \quad w, x, z \in R.$$

Subtracting $5 \times$ (225) from (223), we get

$$(226) \quad f(z)D(z)f(z)wf(x)D(x)f(x)^2 = 0, \quad w, x, z \in R.$$

From (225) and (226), we have

$$(227) \quad f(z)D(z)f(z)wf(x)^2D(x)f(x) = 0, \quad w, x, z \in R.$$

Writing $wf(x)$ for w in (221), it follows that

$$(228) \quad f(z)D(z)f(z)w(f(x)^3D(x) - 2f(x)D(x)f(x)^2) = 0, \quad w, x, z \in R.$$

From (226) and (228), we obtain

$$(229) \quad f(z)D(z)f(z)wf(x)^3D(x) = 0, \quad w, x, z \in R.$$

And left multiplication of (229) by $5f(x)$ gives

$$(230) \quad (5f(z)^2D(z)f(z))wf(x)^3D(x) = 0, \quad w, x, z \in R.$$

Comparing (132) and (230), we have

$$(231) \quad (-3f(z)^3D(z)wf(x)^3D(x) = 0, w, x, z \in R.$$

Since R is 3!-torsion-free, we get from (231)

$$f(z)^3D(z)wf(x)^3D(x) = 0, w, x, z \in R.$$

Let $z = x$ in the above relation. Then we have

$$(232) \quad f(x)^3D(x)wf(x)^3D(x) = 0, w, x \in R.$$

And so, since R is semiprime, we obtain from (232)

$$(233) \quad f(x)^3D(x) = 0, x \in R.$$

Right multiplication of (221) by $f(x)$ gives

$$(234) \quad f(z)D(z)f(z)w(f(x)^2D(x)f(x) - 2D(x)f(x)^3) = 0, w, x, z \in R.$$

Combining (227) with (234), we obtain

$$(235) \quad 2f(z)D(z)f(z)wD(x)f(x)^3 = 0, w, x, z \in R.$$

Since R is 2-tosion-free, we get from (235)

$$(236) \quad f(z)D(z)f(z)wD(x)f(x)^3 = 0, w, x, z \in R.$$

Right multiplication of (236) by x gives

$$(237) \quad f(z)D(z)f(z)wD(x)f(x)^3x = 0, w, x, z \in R.$$

Writing wx for w in (236),

$$(238) \quad f(z)D(z)f(z)wxD(x)f(x)^3 = 0, w, x, z \in R.$$

Comparing (237) and (238), we obtain

$$(239) \quad \begin{aligned} & f(z)D(z)f(z)w[D(x)f(x)^3, x] \\ &= f(z)D(z)f(z)w(f(x)^4 + D(x)g(x)f(x)^2 + D(x)f(x)g(x)f(x) \\ &+ D(x)f(x)^2g(x)) = 0, w, x, z \in R. \end{aligned}$$

Writing $wf(x)^3$ for w in (239),

$$(240) \quad \begin{aligned} & f(z)D(z)f(z)w(f(x)^7 + f(x)^3D(x)g(x)f(x)^2 \\ &+ f(x)^3D(x)f(x)g(x)f(x) + f(x)^3D(x)f(x)^2g(x)) = 0, w, x, z \in R. \end{aligned}$$

Combining (233) with (240), we obtain

$$(241) \quad f(z)D(z)f(z)wf(x)^7 = 0, w, x, z \in R.$$

Left multiplication of (241) by z gives

$$(242) \quad zf(z)D(z)f(z)wf(x)^7 = 0, w, x, z \in R.$$

Writing zw for w in (242), it follows that

$$(243) \quad f(z)D(z)f(z)zwf(x)^7 = 0, w, x, z \in R.$$

Combining (242) with (243), we get

$$(244) \quad \begin{aligned} &(g(z)D(z)f(z) + f(z)^3 + f(z)D(z)g(z))wf(x)^7 \\ &= 0, w, x, z \in R. \end{aligned}$$

On the other hand, replacing $y + tz$ for z in (241), we have

$$(245) \quad \begin{aligned} &f(y + tz)D(y + tz)f(y + tz)wf(x)^7 \\ &\equiv f(y)D(y)f(y)wf(x)^7 \\ &\quad + t\{(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(y)B(y, z))wf(x)^7\} \\ &\quad + t^2U_1(y, z)wf(x)^7 + t^3U_2(y, z)wf(x)^7 \\ &\quad + t^4U_4(y, z)wf(x)^7 + t^5f(z)D(z)f(z)wf(x)^7 \\ &= 0, w, x, y, z \in R. t \in S_3 \end{aligned}$$

where $U_i(y, z), 1 \leq i \leq 4$, denotes the term satisfying the identity (245).

From (241) and (245), we obtain

$$(246) \quad \begin{aligned} &t\{(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(y)B(y, z))wf(x)^7\} \\ &\quad + t^2U_1(y, z)wf(x)^7 + t^3U_2(y, z)wf(x)^7 \\ &\quad + t^4U_4(y, z)wf(x)^7 = 0, w, x, y, z \in R. \end{aligned}$$

Since R is $4!$ -torsion-free by assumption, by Lemma 2.1 the relation (246) yields

$$(247) \quad \begin{aligned} &(B(y, z)D(y)f(y) + f(y)D(z)f(y) + f(y)D(y)B(y, z))wf(x)^7 \\ &= 0, w, x, y, z \in R. \end{aligned}$$

Substituting y^2 for z in (247), we obtain

$$\begin{aligned} &(3(f(y)yD(y)f(y) + f(y)D(y)yf(y)) + 2(yf(y)D(y)f(y) \\ &\quad + f(y)D(y)f(y)y))wf(x)^7 = 0, w, x, y, z \in R. \end{aligned}$$

From (241) and the above relation we obtain

$$(248) \quad 3(f(y)yD(y)f(y) + f(y)D(y)yf(y))wf(x)^7 = 0, w, x, y, z \in R.$$

Comparing (241) and (248), we have

$$(249) \quad 3(g(y)D(y)f(y) - f(y)D(y)g(y))wf(x)^7 = 0, \quad w, x, y, z \in R.$$

Since R is 3!-torsion-free, using (241) we get from (249)

$$(250) \quad (g(y)D(y)f(y) - f(y)D(y)g(y))wf(x)^7 = 0, \quad w, x, y, z \in R.$$

Let $y = z$ in (244). Then it is obvious that

$$(251) \quad (g(y)D(y)f(y) + f(y)^3 + f(y)D(y)g(y))wf(x)^7 = 0, \quad w, x, z \in R.$$

Combining (250) with (251), we obtain

$$(252) \quad (f(y)^3 + 2f(y)D(y)g(y))wf(x)^7 = 0, \quad w, x, y \in R.$$

Left multiplication of (252) by $f(y)^4$ gives

$$(253) \quad (f(y)^7 + 2f(y)^5D(y)g(y))wf(x)^7 = 0, \quad w, x, y \in R.$$

Combining (233) with (253), we obtain

$$f(y)^7wf(x)^7 = 0, \quad x, w \in R.$$

Let $y = x$ in the above relation.

$$(254) \quad f(x)^7wf(x)^7 = 0, \quad w, x \in R.$$

Then since R is semiprime, we obtain from (254)

$$f(x)^7 = 0, \quad x \in R.$$

□

The following theorem as our main theorem generalizes the results of J. Vukman's theorem [12].

Theorem 2.6. *Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that*

$$D(x)^2[D(x), x] \in \text{rad}(A)$$

for all $x \in A$. Then we have $D(A) \subseteq \text{rad}(A)$.

Proof. By the result of B.E. Johnson and A.M. Sinclair [5] any linear derivation on a semisimple Banach algebra is continuous. Sinclair [8] has proved that every continuous linear Jordan derivation on a Banach algebra leaves the primitive ideals of A invariant. Hence for any primitive ideal $P \subseteq A$ one can introduce a linear Jordan derivation $D_P : A/P \rightarrow A/P$, where A/P is a prime and factor Banach algebra, by $D_P(\hat{x}) = D(x) + P$, $\hat{x} = x + P$. Then D is a derivation on A/P . By the assumption

that $D(x)^2f(x) \in \text{rad}(A)$. $x \in A$, we obtain $(D_P(\hat{x}))^2[D_P(\hat{x}), \hat{x}] = 0$, $\hat{x} \in A/P$, since all the assumptions of Theorem 2.4 are fulfilled. And since the prime and factor algebra A/P is noncommutative, from Theorem 2.4 we have $[D_P(\hat{x}), \hat{x}]^7 = 0$, $\hat{x} \in A/P$. And for each P , by the elementary properties of the spectral radius r_P in a Banach algebra A/P , it follows that $r_P([D_P(\hat{x}), \hat{x}]^7) = r_P([D_P(\hat{x}), \hat{x}]^7) = 0$ for all $\hat{x} \in A/P$. Hence we obtain $r_P([D_P(\hat{x}), \hat{x}]) = 0$ for all $\hat{x} \in A/P$. Thus $[D_P(\hat{x}), \hat{x}] \in Q(A/P)$ for all $\hat{x} \in A/P$. On the one hand, since D is continuous, we see that D_P is also continuous. Thus by Theorem 2.3, we obtain $D_P(A/P) \subseteq \text{rad}(A/P)$. But since A/P is semisimple, $D_P(A/P) = \{0\}$ for all primitive ideals of A . Hence we see that $D(A) \subseteq P$ for all primitive ideals of A . And so, $D(A) \subseteq \text{rad}(A)$. On the other hand. In case A/P is a commutative Banach algebra, one can conclude that $D_P = 0$ as well, since A/P is semisimple and since we know that there are no nonzero linear derivations on a commutative semisimple Banach algebra. In other words. $D(x) \in P$ for all primitive ideals of A and all $x \in A$. i.e. we get $D(A) \subseteq \text{rad}(A)$. Therefore in any case we have $D(A) \subseteq \text{rad}(A)$. \square

Theorem 2.7. *Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that*

$$[D(x), x]D(x)^2 \in \text{rad}(A)$$

for all $x \in A$. Then we have $D(A) \subseteq \text{rad}(A)$.

Proof. The proof is similar as in the proof of Theorem 2.6. \square

The following theorem generalizes Vukman's result [11].

Theorem 2.8. *Let A be a noncommutative semisimple Banach algebra. Suppose there exists a linear Jordan derivation $D : A \rightarrow A$ such that*

$$D(x)^2[D(x), x] = 0$$

for all $x \in A$. Then we have $D = 0$.

Proof. According to the result of B.E. Johnson and A.M. Sinclair [5] every linear derivation on a semisimple Banach algebra is continuous. A.M. Sinclair [8] has proved that any continuous linear derivation on a Banach algebra leaves the primitive ideals of A invariant. Hence for any primitive ideal $P \subseteq A$ one can introduce a derivation $D_P : A/P \rightarrow A/P$, where A/P is a prime and factor Banach algebra. by $D_P(\hat{x}) = D(x) + P$, $\hat{x} = x + P$. From the given assumptions $D(x)^2f(x) = 0$. $x \in A$, it follows that $(D_P(\hat{x}))^2[D_P(\hat{x}), \hat{x}] = 0$. $\hat{x} \in A/P$, since all the assumptions of Theorem

2.4 are fulfilled. And also the prime and factor algebra A/P is noncommutative. Hence by Theorem 2.5 we have $[D_P(\hat{x}), \hat{x}]^7 = 0$, $\hat{x} \in A/P$. Then $r_P([D_P(\hat{x}), \hat{x}]^7) = r([D_P(\hat{x}), \hat{x}]^7) = 0$ for all $\hat{x} \in A/P$. Hence we obtain $r_P([D_P(\hat{x}), \hat{x}]) = 0$ for all $\hat{x} \in A/P$. Thus $[D_P(\hat{x}), \hat{x}] \in Q(A/P)$ for all $\hat{x} \in A/P$. On the other hand, since D is continuous, we see that D_P is also continuous. Thus by Theorem 2.3, one obtains $D_P(A/P) \subseteq \text{rad}(A/P)$. But since A/P is semisimple, $D_P(A/P) = \{0\}$. Hence we get $D(A) \subseteq P$ for all primitive ideals P of A . Thus $D(A) \subseteq \text{rad}(A)$. But since A is semisimple, $\text{rad}(A) = \{0\}$. And so, $D = 0$. On the other hand, in case A/P is a commutative Banach algebra, one can conclude that $D_P = 0$ as well since A/P is semisimple and since we know that there are no nonzero linear derivations on a commutative semisimple Banach algebras. In other words $D(x) \in \cap P = \{0\}$ for all primitive ideals and all $x \in A$. And so Thus $D = 0$. Therefore in any case we have $D \equiv 0$. \square

We generalize the result of J. Vukman [11].

Theorem 2.9. *Let A be a noncommutative semisimple Banach algebra. Suppose there exists a linear Jordan derivation $D : A \rightarrow A$ such that*

$$[D(x), x]D(x)^2 = 0$$

for all $x \in A$. Then we have $D = 0$.

Proof. The proof is similar as in the proof of Theorem 2.8. \square

Corollary 2.10. *Let A be a noncommutative semisimple Banach algebra. Suppose there exists a linear Jordan derivation $D : A \rightarrow A$ such that*

$$D(x)[D(x), x] = 0$$

for all $x \in A$. Then we have $D = 0$.

Corollary 2.11. *Let A be a noncommutative semisimple Banach algebra. Suppose there exists a linear Jordan derivation $D : A \rightarrow A$ such that*

$$[D(x), x]D(x) = 0$$

for all $x \in A$. Then we have $D = 0$.

Note: By a simple calculation, if R is a 3!-semiprime ring and $D : R \rightarrow R$ is a Jordan derivation on R with $[D(x), x]D(x) = 0$ or $D(x)[D(x), x] = 0$ for all $x \in R$, we have $[D(x), x]^2 = 0$ for all $x \in R$.

As a special case of Theorem 2.8 we get the following result which characterizes commutative semisimple Banach algebras.

Corollary 2.12. *Let A be a semisimple Banach algebra. Suppose*

$$[x, y]^2 [[x, y], x] = 0$$

for all $x, y \in A$. In this case, A is commutative.

As a special case of Theorem 2.9 we get the following result which characterizes commutative semisimple Banach algebras.

Corollary 2.13. *Let A be a semisimple Banach algebra. Suppose*

$$[[x, y], x][x, y]^2 = 0$$

for all $x, y \in A$. In this case, A is commutative.

As a special cases (Theorem in [11]) of Theorem 2.6 we have the following result.

Corollary 2.14. *Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that*

$$D(x)[D(x), x] \in \text{rad}(A)$$

and for all $x \in A$. Then we have $D(A) \subseteq \text{rad}(A)$.

As a special case (Theorem in [11]) of Theorem 2.7 we have the following result.

Corollary 2.15. *Let A be a noncommutative Banach algebra. Suppose there exists a continuous linear Jordan derivation $D : A \rightarrow A$ such that*

$$[D(x), x]D(x) \in \text{rad}(A)$$

and for all $x \in A$. Then we have $D(A) \subseteq \text{rad}(A)$.

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